Ellipse Series Ellipse-E



Ext. GNSS-aided Inertial Navigation Systems



Compact and Robust Inertial Sensors for Reliable Navigation



No Export Restriction



Warranty



Motion Monitoring

& compensation

Ellipse-E features an integrated Inertial Measurement Unit (IMU) and supports a wide range of external GNSS receivers and additional sensors. All inputs are combined using our in-house advanced sensor fusion algorithm to provide accurate position and orientation, even in challenging environments



Compatible with wide range of GNSS receivers



Built-in magnetometer



External sensors input

ARDUPILOT



Compatible drivers

Reliability & Robustness



Dead reckoning capable



Vibration resilient



Auto-adjusting heave



Spoofing & Jamming mitigation OSNMA capable





1-sigma error over the full temperature range for a typical land application

Correction	Single point	RTK	PPK ⁽²⁾
Roll / Pitch	0.1°	0.05°	0.03°
Heading (3)	0.2°	0.2°	0.1°
Horizontal position	1.2 m	0.01 m	0.01 m

⁽¹⁾ Performance depends on GNSS receiver (validated with u-blox and Septentrio)

SENSORS

	Accelerometers	Gyroscopes	Magnetometers
Measurement range	Land/Air: 20 g	Marine: 450°/s Land/Air: 450°/s High dynamics: 1000°/s	50 Gauss
In run bias	14 ug	7°/h	1.5 mGauss

INTERFACES

Aidings	GNSS, RTCM, Odometer, DVL, Magnetometers, Air data
Protocols	NMEA, sbgEcom (binary), REST API, third party protocols
Output rate	1 kHz (IMU & INS)
Main Serial Interface	RS-232, RS-422, USB - up to 2 Mbps
CAN interface	CAN 2.0 A/B - up to 1 Mbps
Sync I/O	4x Sync inputs (RS232), 2x Sync output (TTL)

VERSIONS

Box version are IP68, resistant to dust and water. OEM version are PCB mounted for tight integration.

	Box 60	OEM OEM
Dimensions	46 x 45 x 24 mm	29.5 x 25.5 x 11 mm
Weight	49 g	8 g

LONG GNSS OUTAGE PERFORMANCE⁽¹⁾

Application	Position accuracy
Land	0.5% travelled distance
Marine	1.0% travelled distance
Airborne	2.0% travelled distance

⁽¹⁾ With external aiding inputs. Test report available upon request.

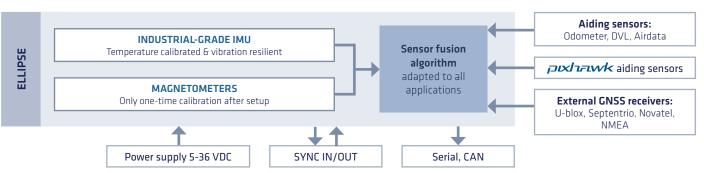
HEAVE PERFORMANCE Marine version

Accuracy	5 cm or 5%	Whichever is greater
Wave period	0 to 20 s	Auto-adjusting

ELECTRICAL & ENVIRONMENTAL

Input voltage	5 - 36 VDC
Power consumption	< 300 mW
Operating temperature	-40 to 85 °C
Shock limit	500 g / 0.1 ms
Operating vibration	8 g RMS (20 Hz to 2 kHz per MIL-STD 810G)
MTBF	218,000 hours

FUNCTIONAL BLOCK DIAGRAM



Free Technical Support

Lifetime Firmware Updates

2-year Warranty





⁽²⁾ Using Qinertia post processing software

⁽³⁾ Single / dual antenna

Ellipse Series Ellipse-N/D



GNSS-aided Inertial Navigation Systems



Compact and Robust Inertial Sensors for Reliable Navigation



No Export Restriction



Warranty



Motion Monitoring

& compensation

The Ellipse INS series combines Inertial Measurement Unit (IMU) with GNSS and external sensors using our advanced fusion algorithm, delivering accurate position and orientation, even in challenging environments.



RTK capable



Built-in magnetometer



External sensors input

ARDUPILOT

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Compatible drivers

Reliability & Robustness



Dead reckoning capable



Vibration resilient



Auto-adjusting heave



Spoofing & Jamming mitigation OSNMA capable





SYSTEM PERFORMANCE

1-sigma error over the full temperature range for a typical land application

Correction	Single point	RTK	PPK ⁽¹⁾	
Roll / Pitch	0.1°	0.05°	0.03°	
Heading	0.2°	0.2°	0.1°	
Horizontal position	1.2 m	0.01 m	0.01 m	

⁽¹⁾ Using Qinertia post processing software

SENSORS

	Accelerometers	Gyroscopes	Magnetometers
Measurement range	Land/Air: 20 g	Marine: 450°/s Land/Air: 450°/s High dynamics: 1000°/s	50 Gauss
In run bias instability	14 ug	7°/h	1.5 mGauss

INTERFACES

Aidings	GNSS, RTCM, Odometer, DVL, Magnetometers, Air data
Protocols	NMEA, sbgEcom (binary), REST API, third party protocols
Output rate	1 kHz (IMU & INS)
Main Serial Interface	RS-232, RS-422, USB - up to 2 Mbps
CAN interface	CAN 2.0 A/B – up to 1 Mbps
Sync I/O	2x Sync inputs (RS232), 1x Sync output (TTL)

LONG GNSS OUTAGE PERFORMANCE(1)

Application	Position accuracy
Land	0.5% travelled distance
Marine	1.0% travelled distance
Airborne	2.0% travelled distance

⁽¹⁾ With external aiding inputs. Test report available upon request.

HEAVE PERFORMANCE Marine version

Accuracy	5 cm or 5%	Whichever is greater
Wave period	0 to 20 s	Auto-adjusting

INTERNAL GNSS

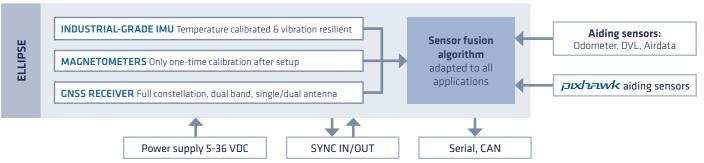
Features	RAW, OSNMA, PointPerfect (SPARTN/ RTCM), SBAS	
Signals	GPS: L1C/A, L2C GLONASS: L10F, L20F	GALILEO: E1, E5b BEIDOU: B1/B2
Time to first fix	< 24 s (cold start)	
Jamming / Spoofing	Mitigation & advanced indicators	

ELECTRICAL & ENVIRONMENTAL

Input voltage	5 - 36 VDC
Power consumption	N ⁽¹⁾ : < 600 mW, D ⁽¹⁾ : < 900 mW
Operating temperature	-40 to 85 °C
Shock limit	500 g / 0.1 ms
Operating vibration	8 g RMS (20 Hz to 2 kHz per MIL-STD 810G)
MTBF	218,000 hours

⁽¹⁾ Without GNSS antenna

FUNCTIONAL BLOCK DIAGRAM



Free Technical Support

Lifetime Firmware Updates

2-year Warranty





Ellipse Series Ellipse-A



Attitude and Heading Reference System



Compact & Robust Inertial Sensors for Accurate Orientation & Heave



No Export Restriction



Warranty





The Ellipse AHRS series integrates Inertial Measurement Unit (IMU) with magnetometers to provide reliable orientation & heave in both low and high dynamic environments & mitigate the transient magnetic disturbances.



Reliable roll, pitch and heading



Immunity to transient magnetic disturbances

ARDUPILOT

Compatible drivers

Accurate & Reliable Orientation



Vibration resilient





Built-in magnetometers with advanced magnetic calibration





Each of our sensors is subjected to a thorough calibration and testing process across its entire operating temperature range, at our manufacturing facilities. This guarantees all delivered products will meet their specifications for their entire lifetime without the need for a recalibration.

SYSTEM PERFORMANCE 1-sigma error over the full temperature range.

Environment	Static	Dynamics ⁽²⁾
Roll / Pitch	0.1°	0.4°
Heading ⁽¹⁾	0.8°	1°

⁽¹⁾ Magnetic heading under homogeneous magnetic field after calibration

SENSORS

	Accelerometers	Gyroscopes	Magnetometers
Measurement range	Marine: 8 g Land/Air: 20 g High Dynamics: 40 g	Marine: 450°/s Land/Air: 450°/s High Dynamics: 1000°/s	50 Gauss
Scale factor error	1000 ppm	500 ppm	< 0.5%
Long term bias repeatability	1.5 mg	500°/h	
In run bias instability	14 ug	7°/h	1.5 mGauss
Random walk	0.03 m/s/√h	0.18 °/√h	3 mGauss
VRE	0.05 mg/g ²	1°/h/g²	-
Bandwidth	390 Hz	133 Hz	22 Hz

INTERFACES

Protocols	sbgEcom (binary), REST API, NMEA, third party protocols
Output rate	Up to 1 kHz (IMU & Euler)
Main Serial Interface	RS-232, RS-422, USB – up to 2 Mbps
CAN interface	CAN 2.0A/B – up to 1 Mbps
Svnc I/O	2x Sync inputs (RS232), 1x Sync output (TTL)

VERSIONS

Box version are IP68, resistant to dust and water. OEM version are PCB mounted for tight integration.

	Box •	OEM W
Dimensions	46 x 45 x 24 mm	29.5 x 25.5 x 11 mm
Weight	45 g	8 g

HEAVE PE	RFORMANCE	Available on marine version
Accuracy	5 cm or 5%	Whichever is greater
Wave period	0 to 20 s	Auto-adjusting

ELECTRICAL & ENVIRONMENTAL

Input voltage	5 - 36 VDC
Power consumption	< 300 mW
Operating temperature	-40 to 85 °C
Shock limit	500 g
Operating vibration	8 g RMS (20 Hz to 2 kHz per MIL-STD 810G)
MTBF	218,000 hours

Communication interface: REST API / C library

FUNCTIONAL BLOCK DIAGRAM

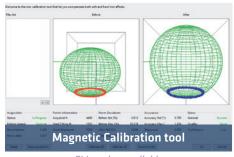
Industrial Grade IMU
Temperature calibrated & vibration resilient

Sensor Fusion Algorithm
Adapted to a wide range of applications

Sync In/OUT

Magnetometers
Requires only one-time calibration

Power supply 5-36 VDC







CLI version available

Free Technical Support

Lifetime Firmware Updates

2-year Warranty





⁽²⁾ Evaluated for typical marine dynamics